

Transfer Learning in Evolutionary Spaces

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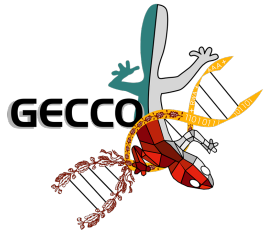
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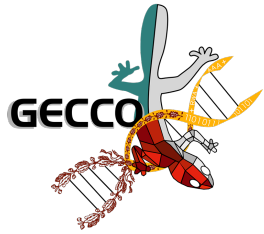


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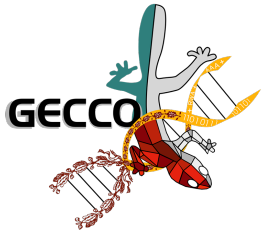
Tutorial Website

<https://www.cs.up.ac.za/cs/npillay/TLEA.htm>



Overview

- Evolutionary spaces
- Transfer learning
- Transfer learning in search
- Benefits of TL in search
- Case study: solution space
- Case study: program space
- Case study: heuristic space
- Case study: design space
- Automated TL in EAs
- Discussion: future research directions



Evolutionary spaces

Solution
space

Program
space

Heuristic
Space

Design
Space



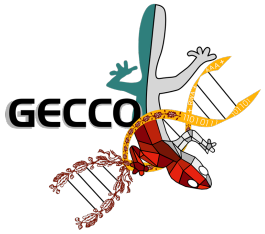
Transfer Learning

- Transfer of knowledge
- What to transfer?
- How to transfer?
- When to transfer?
- Positive vs. negative transfer
- Focus on data and feature transfer
- TL in EC



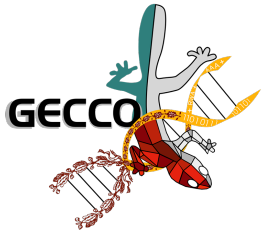
Transfer Learning in Search

- Knowledge learnt during search is transferred
- What is transferred?
 - Points in the search space
 - Elements of the population
 - Components of elements
 - Areas of the search space
- How is it transferred?
 - Forms part of the initial population of the target EA
- When is it transferred?
 - Last generations
 - Generation intervals



Benefits of TL in Search

- Improvement in performance
- Reduction in computational cost
- Reduction in the amount of data needed
- Improved convergence



Case Study: Solution Space

- Genetic algorithms for solving the travelling salesman problem (TSP)
- Symmetric TSP – Involves finding a route of minimum length that visits all cities exactly once and begins and ends at the same city. The distance between cities m and n is the same as the distance between n and m .
- Asymmetric TSP – Involves finding a route of minimum length that visits all cities exactly once and begins and ends at the same city. The distance between cities m and n is not necessarily the same as the distance between n and m .

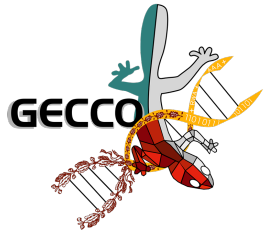


Case Study: Solution Space

- What is the aim of the transfer learning?
- Define the source and target domains
- What will be transferred?
- How will it be transferred?
- When will it be transferred?
- Transformation function needed?

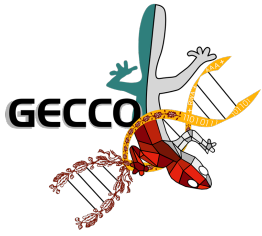
Solution Space TSP

TL Case Study Discussion



Case Study: Program + Heuristic Space – Scheepers and Pillay (2021)

- Genetic programming generation construction hyper-heuristic
- Each point/element – a parse tree representing a heuristic
- Application one dimensional bin packing (1BPP)
- Aim – reduction in computational cost of solving more challenging problems
- Source domain – easy and medium 1 BPP problems
- Target domain – hard 1BPP problems



Case Study: Program + Heuristic Space – Scheepers and Pillay (2021)

- What to transfer
 - Population of last generation (TL1)
 - Best individuals of each generation (TL2)
 - Areas of the search space
 - Frozen root (TL 2.1)
 - Frozen second level (TL2.2)
 - Frozen leaf nodes (TL2.3)
- How to transfer?
- When to transfer?



Case Study: Program + Heuristic Space – Scheepers and Pillay (2021)

- Performance evaluation
 - Objective value – Number of bins
 - Computational effort – Koza computational effort formula

$$f(x, M, i) = R(x, M, i) * M * i$$

$$R(x, M, i) = \lceil \frac{\log(1 - x)}{\log(1 - P(M, i))} \rceil$$

- Generality – Standard deviation of differences (SDD)

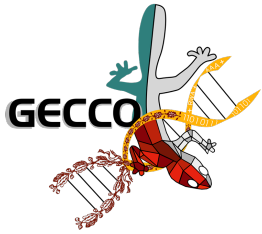
$$SDD(H) = \sqrt{\frac{\sum_{i=1}^N (x_i - \bar{x})^2}{N - 1}}$$

where N is the number of problem instances, $x_i = 0$ if $o_i = 0$ and $b_i = 0$. Otherwise $x_i = (|o_i - b_i|) / \text{average} * 100$.



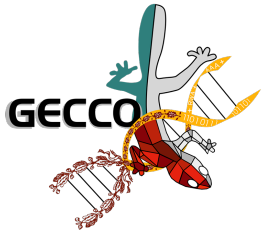
Case Study: Program + Heuristic Space – Scheepers and Pillay (2021)

- Objective value performance
 - TL approaches performed better
 - TL2, TL2.2 and TL2.3 produced the best results
 - Best approach of the three is problem dependent
- Computational effort performance
 - TL2 best computational effort
 - TL2.1, TL2.2, TL2.3 better than TL1
- Generality performance
 - TL1 and TL2 best generality
 - TL2.1, TL2.2, TL2.3 worst generality



Case Study: Heuristic Space

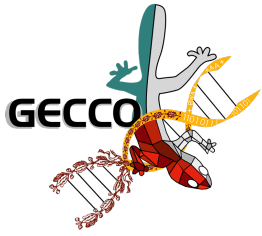
- Selection construction/perturbative genetic algorithm hyper-heuristic for educational timetabling
- Timetabling problems involve allocation of an entities, e.g. exams, classes to timetable slots to reduce hard and soft constraints
- Educational timetabling
 - Examination timetabling
 - University course timetabling
 - School timetabling



Case Study: Heuristic Space

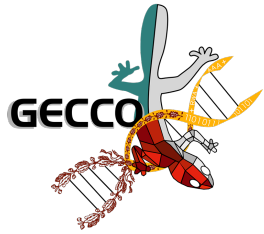
- What is the aim of the transfer learning?
- Define the source and target domains
- What will be transferred?
- How will it be transferred?
- When will it be transferred?

Heuristic Space Educational
Timetabling
TL Case Study Discussion



Case Study: Heuristic Space (Singh and Pillay 2022)

- Ant colony optimization generation construction hyper-heuristic
- Aim: Reduction in computational cost
- Applications
 - Movie scene scheduling problem
 - Quadratic assignment problem
 - One dimensional bin packing
- Source domain: Simpler problem instance/s
- Target domain: Complicated problem instance/s



Case Study: Heuristic Space (Singh and Pillay 2022)

- What is transferred?
 - Pheromone maps from of the last iteration of the ACO
- How is it transferred?
 - Best pheromone map of the last iteration of the source ACO hyper-heuristic is transferred
- When is it transferred?
 - Used at the beginning of the target ACO hyper-heuristic instead of creating the maps randomly
- Performance
 - Drastic reduction in computational cost
 - Improvement in objective value for MSSP and QAP, poorer objective values for 1BPP



Case Study: Program Space

- Genetic programming for evolving prediction models for disease diagnosis
- Given relevant patient attributes the model predicts whether the patient has the disease or not
- Disease diagnosis
 - Heart disease
 - Diabetes
 - COVID-19

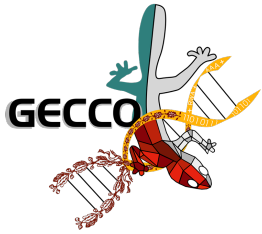


Case Study: Program Space

- What is the aim of the transfer learning?
- Define the source and target domains
- What will be transferred?
- How will it be transferred?
- When will it be transferred?

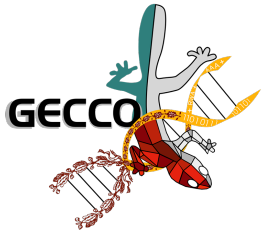
Program Space Prediction

TL Case Study Discussion



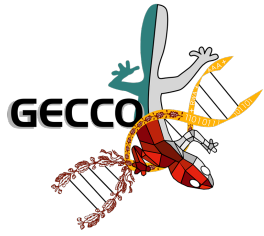
Case Study: Design Space – Nyathi and Pillay (2021)

- Automated design of the genetic programming algorithm to produce classifiers
- Design decisions represented in chromosome
 - Representation
 - Parameter values
 - Genetic operators
 - Control flow
- Grammatical evolution used for automated design (AutoGE)
- Source domain: NSL-KDD
- Target domain: UCI benchmark set



Case Study: Design Space – Nyathi and Pillay (2021)

- What is transferred?
 - Design of the GP classification algorithm
- How is it transferred?
 - Best performing designs from the source AutoGE to the target AutoGE
- When is it transferred?
 - Best performing designs form the initial population generation of the AutoGE
- Performance
 - Improved accuracy with using transfer learning
 - Reduction in computational cost



Differences/Similarities for Different Spaces

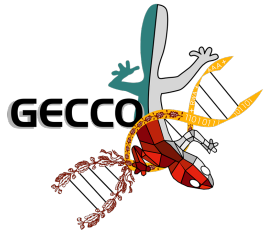
- Benefit/aim of transfer learning
- What to transfer?
- How to transfer?
- When to transfer?
- Performance
- Challenges



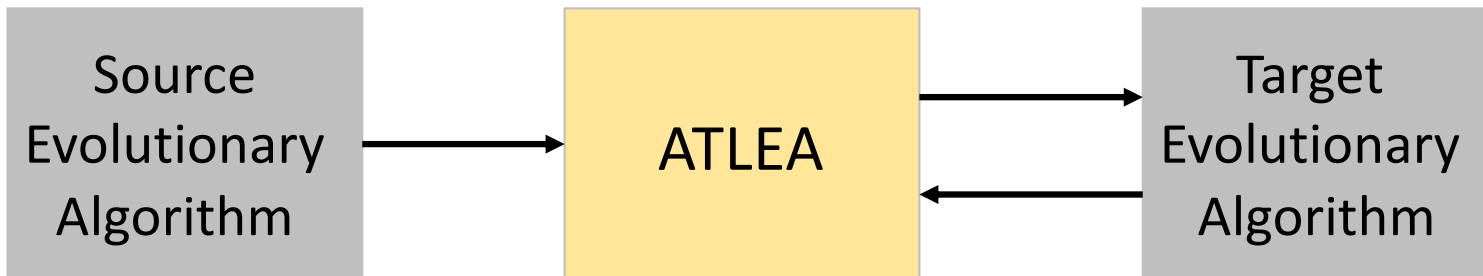
Automated Transfer Learning

- Automating TL design decisions
- Design decision
- Approaches
 - Selection perturbative hyper-heuristic – single point hyper-heuristic applied to randomly created design
 - Genetic algorithm – Each chromosome is a design
- Automated transfer learning for evolutionary algorithms (ATLEA)

ATLEA: Automated Transfer Learning in Evolutionary Algorithms



ATLEA





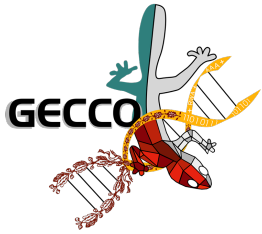
Automated Transfer Learning in ATLEA

- Selection perturbative hyper-heuristics
 - Random heuristic select, accept improving moves
 - Choice function, AILTA
- Genetic algorithm
- Extensible



ATLEA Design

- How many elements to transfer from each generation?
- Percentage of the element to transfer?
- Design syntax
 - A component for each generation
 - Number of elements to transfer
 - Percentage of the element to transfer



Basic Selection Perturbative Hyper-Heuristic

- Randomly select heuristic
- Accept if there is an improvement in performance
- Perturbative heuristics
 - swap
 - swapn
 - replace
- Abstract methods
 - evaluate
 - isBetter

Discussion: Future Research Directions